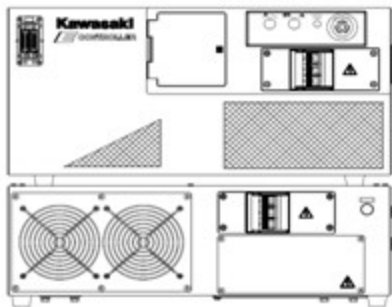




D=580

470



550

[2] Controller		
1. Model	E01	
2. Enclosure	Enclosed structure / Indirect cooling system	
3. Dimensions	See attached drawing	
4. Number of controlled axes	Max.9 axes (standard 7 axes, option 2 axes)	
5. Servo control and drive system	Full Digital Servo System	
6. Type of control	Teach mode	Joint, Base, Tool, Fixed Tool (option) operation mode
	Repeat mode	Joint, Linear, Circular (option) interpolation
7. Teaching method	Teaching or AS language programming	
8. Memory capacity	8 MB	
9. External operation signals	External Emergency stop, External Hold, etc.	
10. Number of IO slots	3 slots	
11. Operation panel	Teach/Repeat SW, Emergency Stop SW, Control power lamp	
12. Communication I/F	Ethernet(100BASE-TX) , USB, RS-232C each 2port (1port on panel, 1port inside controller)	
13. Mass	See attached drawing	
14. Power requirement	AC200 V - AC220 V±10%, 50/60 Hz, 3 phases, Max. 5.6 kVA	
15. Ground	Less than 100 Ω (robot dedicated ground) Leakage current: max. 100 mA	
16. Ambient temperature	0 - 45°C	
17. Relative humidity	35 - 85 % (non-condensation)	
18. Color	Munsell: 10GY9/1 equivalent	
19. Teach Pendant	TFT color display (5.7 inch LCD) with touch panel Emergency Stop SW, Teach Lock SW and Enable SW	
20. Safety Circuit	Category: 4, Performance Level: e (EN ISO13849-1) ★	
21. Standard Options		
General purpose IO board	IN:32 OUT:32 NPN(sink) type or PNP(source) type	
Arc Interface	Arc interface add-on board	
Fast check mode	Fast check mode Switch	
TP sheet language	English or Japanese or Chinese	
I/O connector	D-SUB 37pin(male,female) with cover	
Power/Signal cable	5m, 10m, 15m	
Teach Pendant cable	5m, 10m, 15m	
Transformer unit	AC400V / AC460V by tap selection	
22. Other Options		
Additional IO board	IN:64/96 OUT:64/96 NPN(sink) type or PNP(source) type	
Motor brake release	Manual brake release switch BOX	
PC cable (RS-232C)	1.5 m, 3 m	
External axes control	Additional amplifier and harnesses for external axes	
Extended safety functions	Cubic-S(Motion area monitoring, Joint monitoring, Speed monitoring etc)	
Teach Pendant option	Connector for TP less	
Others	Field BUS, Software PLC, Analog input/output, Conveyor Synchronization	
23. Others	Consult Kawasaki about maintenance parts and spare parts.	

★ Category and Performance level (PL) are determined by the whole system and conditions.
The safety circuit of this controller is available in the system of category: up to 4, PL: up to e.